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# ABSTRACT

An interactive system for a local intervention inside a region of a non-homogeneous structure, such as the skull of a patient, which is related to the frame of reference ( $R_2$ ) of an operation table, and which is connected to a reference structure comprising a plurality of base points. The system creates on a screen a representation of the non-homogeneous structure and of the reference structure connected thereto, provides the coordinates of the images of the base points in the first frame of reference ( $R_1$ ), allows the marking of the coordinates of the base points in  $R_2$ , and allows the carrying out of the local intervention with an active member such as a trephining tool, a needle, or a radioactive or chemical implant. The system also optimizes the transfer of reference frames between  $R_1$  and  $R_2$ , from the coordinates of the base points in  $R_2$  and the images in  $R_1$  by reducing down to a minimum the deviations between the coordinates of images in  $R_1$  and the base points in  $R_1$  after transfer. The system also establishes real time bi-directional coupling between: (1) an origin and a direction of intervention simulated on the screen, (2) the position of the active member.

16 Claims, 13 Drawing Sheets